## Topics in Discrete Mathematics

 Part 2: Introduction to Graph Theory
## Lecture 1

 Graphs- Definition of a graph
- Common examples: $K_{n}, P_{n}, C_{n}$
- Degrees and the handshake lemma
- Graph isomorphism
- Subgraphs and unions


### 1.1 Definitions and examples

Graphs are things that look like this:


We have a some blobs, called vertices, joined by lines, called edges.
We can think of the vertices as objects, and the edges representing relations between pairs of objects. For example, the vertices might represent towns and the edges roads between them. Or the vertices might represent computers and the edges wired connections between them.
But these collections of blobs and lines can fascinating as objects of mathematics interest in their own right.

We will define edges by the two vertices at their ends. This gives the following definition, the most important of the course:

Definition 1.1. A graph $G=(V, E)$ consists of a nonempty set $V$ of vertices and a set

$$
E \subseteq V^{(2)}:=\{\{u, v\}: u, v \in V, u \neq v\}
$$

of unordered pairs from $V$ called edges.
If $u, v \in V$ are vertices and $e=\{u, v\} \in E$ is an edge between them, we say that $u$ and $v$ are adjacent, and that $e$ is incident to $u$ and $v$.
The number of vertices $n=|V|$ is called the order of $G$, and the number of edges $m=|E|$ is called the size of $G$.

Throughout we will abbreviate an edge $\{u, v\}$ as just $u v$. Remember that these are unordered pairs, so $u v$ and $v u$ denote the same edge.

Here are some common examples of graphs with $n$ vertices.
Example 1.2. The complete graph $K_{n}$ on $n$ vertices is defined by

$$
V=[n]=\{1,2, \ldots, n\}, \quad E=V^{(2)}=[n]^{(2)}=\{12,13,14, \ldots,(n-1) n\} .
$$


$K_{1} \quad K_{2}$

$K_{4}$

We call $K_{1}$, with one vertex and no edges the trivial graph. Some theorems in this course apply to nontrivial graphs - that is, graphs with two or more vertices.

Note that we can also draw $K_{4}$ as

where none of the edges cross each other. In Lecture 4 we'll talk more about graphs that can be drawn without edge crossings.

Example 1.3. The path $P_{n}$ on $n \geq 2$ vertices (so of length $n-1$ ) is defined by


Example 1.4. The cycle $C_{n}$ on $n \geq 3$ vertices is defined by

$$
V=[n], \quad E=\{12,23,34, \ldots,(n-1) n, n 1\} .
$$


$C_{3}$

$C_{4}$

$C_{5}$

$C_{6}$

Note that $P_{2}=K_{2}$ and $C_{3}=K_{3}$ - the latter graph is often called the triangle.
Example 1.5. A graph that will pop up a few times in this course is the Petersen graph shown below:


For reasons will see in a moment, we haven't labelled the vertices. But note that if we had, the graph would be unambiguously defined by the picture - so we'll often not write down $V$ and $E$ explicitly for graphs we consider.

Looking carefully at Definition 1.1, it's worth emphasising a few points:

- The edge set $E$ is a set, so can include each pair $u v$ at most once. So we are not allowed multiple edges between vertices.
- Edges $u v$ have to be between distinct vertices. So we can't have a 'loop' from a vertex to itself.

Note that some textbooks differ from our convention here, and refer to our graphs - no multiple edges, no loops - as 'simple' graphs.

- Edges $u v$ are unordered pairs. So an edge $u v=v u$ goes between vertices $u$ and $v$ an are never 'directed' from one vertex to another.

Directed graphs are interesting in their own right, but are outside the scope of this course (except for the final question on the Problem Sheet).

- Edges uv consist of pairs of vertices. So we don't have 'hyperedges' between three or more vertices.

Again, 'hypergraphs' with these hyperedges are interesting but outside our scope.

- Although our definition allows $V$ to be infinite, from now on we always assume (unless we say otherwise) that our graphs have a finite number of vertices.

Keen students can consider it an exercise to work out which theorems in this coursealso hold when $V$ is countable or uncountably infinite.

Definition 1.6. Consider a graph $G=(V, E)$. The degree $d(v)$ of a vertex $v \in V$ is defined as the number of edges incident to $v$ :

$$
d(v):=|\{e \in E: v \in e\}| .
$$

Equivalently, $d(v)$ is the number of vertices adjacent to $v$

$$
d(v)=|\{u \in V: v u \in E\}| .
$$

The seqence of degrees $(d(v): v \in V)$, usually written in decreasing order, is called the degree sequence of $G$.

We write $\Delta:=\max _{v} d(v)$ for the maximum degree, and $\delta:=\min _{v} d(v)$ for the minimum degree.

So, for example, the degree sequence of $K_{4}$ is $(3,3,3,3)$ and the degree sequence of $P_{5}$ is $(2,2,2,1,1)$.

Let's make the first theorem of the course an easy one.
Theorem 1.7 (Handshake lemma). The sum of the degrees is twice the number of edges. That is, for a graph $G=(V, E)$, we have

$$
\sum_{v \in V} d(v)=2|E|
$$

In particular, the sum of the degrees is always even.
Proof. Go through the vertices of the graph counting the edges incident of each vertex. This is clearly $\sum_{v} d(v)$. We've now counted each edge exactly twice, once for each vertex it's incident to, which is $2|E|$.

### 1.2 Graph isomorphism

The following graphs are obviously, in some sense, the same graph.




However, $G_{1}$ and $G_{3}$ have different vertex sets, and all three have different edge sets. But the point is that if we relabel the vertices of $G_{2}$ and $G_{3}$, then they can be made equal.
If graphs can be relabelled to be made equal, then we say they are isomorphic. Throughout this course we will consider isomorphic graphs to the same graph (so in particular, we often won't bother to label the vertices of graphs in pictures).

Definition 1.8. Two graphs $G=(V, E)$ and $G^{\prime}=\left(V^{\prime}, E^{\prime}\right)$ are isomorphic if there exists a bijection $\phi: V \rightarrow V^{\prime}$ such that $u v \in E$ is an edge in $G$ if and only if $\phi(u) \phi(v) \in E^{\prime}$ is an edge in $G^{\prime}$.

So we can show that $G_{1}$ and $G_{3}$ above are isomorphic by writing down the isomorphism

$$
\phi(1)=a, \quad \phi(2)=b, \quad \phi(3)=c .
$$

### 1.3 New graphs from old

To concepts it will be useful to have are that of the subgraph and of graph unions.
Definition 1.9. A graph $G^{\prime}=\left(V^{\prime}, E^{\prime}\right)$ is a subgraph of another graph $G=(V, E)$ if $V^{\prime} \subseteq V$ and $E^{\prime} \subseteq E \cap V^{\prime(2)}$.

In other words, to get to a subgraph, we can first delete some vertices, we then must delete all edges incident to those vertices, and then we can further delete more edges.
As ever, we will consider a graph $H$ to be a subset of a graph $G$ if $G$ contains a subgraph isomorphic to $H$.

So, for example, $K_{4}$ and $P_{3}$ are both subgraphs of $K_{5}$.

$K_{4}$

$P_{3}$

The graph union is what you get by simply drawing to graphs next to each other.
Definition 1.10. Consider two graphs $G_{1}=\left(V_{1}, E_{1}\right)$ and $G_{2}=\left(V_{2}, E_{2}\right)$ with disjoint vertex sets. The graph union is defined by $G_{1} \cup G_{2}:=\left(V_{1} \cup V_{2}, E_{1} \cup E_{2}\right)$.

Again, if the vertex sets are not disjoint, we will replace one of the graphs by an isomorphic copy such that the vertex sets are disjoint. Hence the single graph shown below is $K_{3} \cup C_{4}$.


Next time: Taking walks around graphs: paths, trails, cycles and circuits.

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